

Active Filters using Single Current Conveyor

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Abstract

A current to voltage lowpass filter using a single CCII is proposed. This filter can absorb all finite CCII resistances and capacitances and offer both non-inverting and inverting output. Convenient compensation methods exist for gain inaccuracy and excess phase effects. The sensitivities are also very low. The filter is particularly useful for data converting and sampled-data filtering systems as it can fulfil both filtering for antialiasing or smoothing purpose and interfacing between current-mode and voltage-mode systems. We also present a current-mode filter topology using a single dual output CCII, which can realise various types of lowpass, bandpass and highpass filters. Since the output current is taken from one CCII output terminal, the structure is suitable for direct cascade for high-order filter design and less sensitive to the CCII parasitic effects compared with those taking current output from capacitor or resistor branches. Both voltage- and current-mode high-order filters can be readily realized using the proposed two filters as basic sections.

1. Introduction

Two integrator loop filters using multiple amplifiers have been most widely used [1-4]. Recently active filters using a single amplifier have also received much interest in video signal processing and wireless communication systems [1, 5-7]. Also, between the two types of topology, a new filter structure which contains two integrator loops, but uses a single amplifier has been proposed [8]. Single amplifier biquads have some attractive features such as low power consumption, low noise, small size, and wide linearity. Active filters using a single op-amp have been used for several decades and most recently they have been used in

wireless transceivers, utilising a fully differential voltage buffer [5] or a differential difference amplifier [6]. Active filters based on a single OTA with a single output or multiple outputs, in both the voltage- and current-mode have been systematically investigated in [1]. Single CCII filter design has also received some attention [7, 9, 10]

In switched-current signal processing, antialiasing and post smoothing lowpass filters are needed and also current-mode circuits need to interface with voltage-mode circuits. It would be therefore desirable to have a single circuit which can perform both filtering and interfacing (rather than two separate circuits) to reduce the system complexity, power, size and cost. For this purpose, a voltage to current lowpass filter suitable for use at the input of a switched-current circuit has been developed using a single dual output CCII [11-16]. In this paper we propose a current to voltage lowpass filter for use at the output of a switched-current circuit for smoothing filtering and interfacing with the voltage-mode system. Not limited to switched-current circuits, the argument also applies to current-mode data converters which also need antialiasing and post smoothing filters and to interface voltage-mode systems. Furthermore, for voltage-mode switched-capacitor circuits and voltage-mode data converters, the proposed filter can also find use at the input of the system for antialiasing lowpass filtering and interfacing with the current-mode system.

Most CCII-RC filters in the literature use single output CCII and most current-mode CCII-RC filters take output currents from capacitor or resistor branches. Such current output methods increase the effects of nonideal CCII input and output impedances

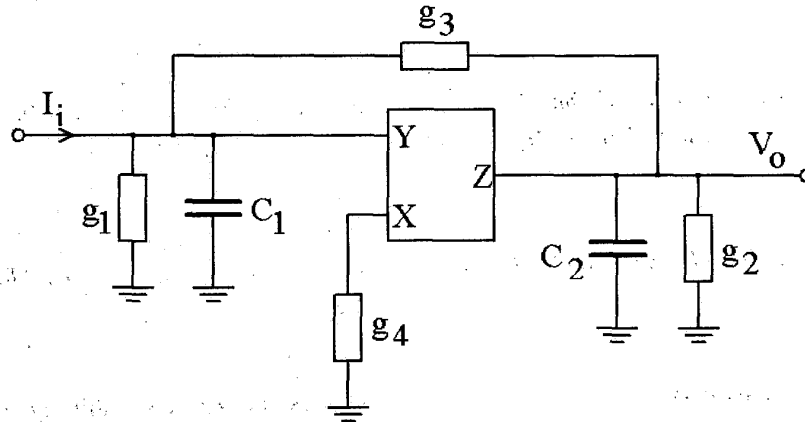


Figure 1. Current to voltage lowpass filter using single CCII

and parasitic node capacitances, and cause coupling if the driven stage does not have zero input impedance in the cascade design. Utilizing the current following and virtual grounding property of the CCII

with Y terminal grounded, we may insert extra CCII's into the associated branches to take current outputs. But the nonidealities of these extra CCII's will severely degrade the filter performance and this method will also increase component count. Multiple output CCII's can be used to solve the above problems in the generation of current-mode filter structures, since using the multiple output terminals, current output and current feedback can be readily accomplished. A comprehensive set of current-mode two integrator loop filters using dual output CCII's (DO-CCII) have been proposed [4]. This paper is concerned with current-mode filters using a single DO-CCII.

2. Current To Voltage Lowpass Filter Using Single CCII

The proposed current to voltage single CCII lowpass filter is shown in Figure 1. Its transfer function can be derived as

$$\frac{V_o}{I_i} = \frac{g_3 - g_4}{as^2 + bs + c} \quad (1)$$

There into,

$$a = C_1 C_2 \quad (2)$$

$$b = C_1(g_2 + g_3) + C_2(g_1 + g_3) \quad (3)$$

$$c = (g_1 g_2 + g_1 g_3 + g_2 g_3 + g_3 g_4) \quad (4)$$

The gain polarity can be controlled by g_3 and g_4 . The non-inverting function can be achieved by selecting $g_3 > g_4$, and the inverting function by $g_3 < g_4$.

There are choices for the filter design. For example, we may choose $g_1 = g_2 = g$ and $C_1 = C_2 = C$, then determine g , g_3 and g_4 for a set C and the required gain, K , cut-off frequency, ω_0 and quality factor, Q . The formulae for a normalised frequency, $\omega_0 = 1$, are given by $g_3 = (1/4Q^2 - 1)/K$, $g_4 = g_3 - K^2 C^2$, and $g = C/2Q - g_3$.

The ω_0 and Q sensitivities of the filter are very low. For the above design, for example, the sensitivities of ω_0 and Q with respect to C_1 and C_2 are -0.5 and 0 , respectively. The sensitivities of Q to g_1 , g_2 and g_3 are equal to 0.5 . All the other sensitivities of ω_0 and Q are no larger than 0.5 .

The finite admittances at terminals Y and Z of the CCII can be modelled as $Y_y = G_y + sC_y$ and $Y_z = G_z + sC_z$ connected from respective terminals to ground. The finite impedance at terminal X may be modelled as a series resistance R_x . These finite admittances/impedances will influence filter performance adversely [12]. From the filter structure in Figure 1, we can observe that R_x can be absorbed by the external resistance connected from terminal X to ground. Also the external resistors and capacitors at terminals Y and Z all are grounded and thus can be used to absorb the CCII finite conductances and capacitances at these terminals. The filter therefore is free from the effects of finite CCII impedances.

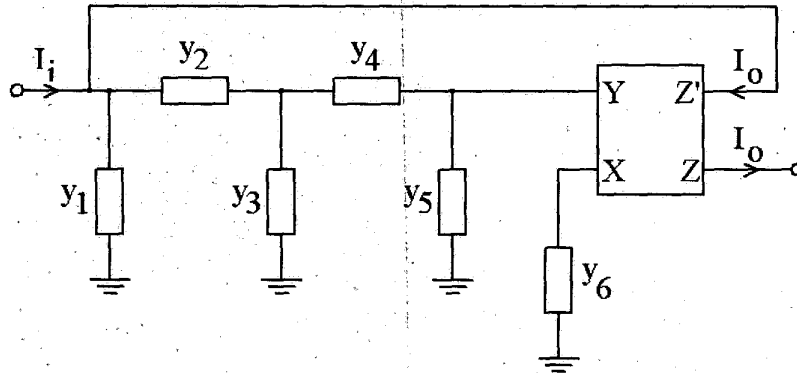


Figure 2 Current-mode filter using single DO-CCII

The CCII is essentially composed of a voltage buffer denoted by δv and δi respectively may be defined as $V_x = (1 + \delta v)V_y$, and $I_z = (1 + \delta i)I_x$ [13]. For the nonideal CCII we can readily prove $I_z = g_4(1 + \delta i)(1 + \delta v)V_y = g_4'V_y$, where $g_4' = g_4(1 + \delta i)(1 + \delta v)$. Hence the effect of the tracking errors may be equivalently considered to cause the change in the conductance of the g_4 resistor. Therefore the effects of CCII buffering errors on filter performances can be very easily evaluated by directly substituting g_4' for g_4 in the transfer function.

To eliminate the effects of buffering errors we can add a resistor in parallel or series with the g_4 resistor to accommodate the buffering errors [13]. When $(1 + \delta v)(1 + \delta i) < 1$, parallel compensation should be adopted. The corresponding compensation equation is then readily derived as $(1 + \delta v)(1 + \delta i)(g_4 + g_{4cp}) = g_4$, from which we can determine the parallel compensation conductance as $g_{4cp} = g_4[1/(1 + \delta v)(1 + \delta i) - 1]$. When $(1 + \delta v)(1 + \delta i) > 1$, series compensation should be utilized and in this case the compensation equation becomes $(1 + \delta v)(1 + \delta i)g_4 g_{4cs} / (g_4 + g_{4cs}) = g_4$, which gives the series compensation conductance as $g_{4cs} = g_4 / [(1 + \delta v)(1 + \delta i) - 1]$.

The excess phase of the CCII will pose a stability problem at higher frequencies [12]. For the given CCII, to extend the working frequency of the filter, we must overcome the finite bandwidth effects. The passive compensation technique using a capacitor can be used. For the CCII, suppose that $V_x/V_y = 1/(1 + s\tau_v)$, and $I_z/I_x =$

and a current buffer. Voltage and current tracking errors $1/(1 + s\tau_i)$, then $I_z = YV_y$, where $Y = g_4 / [(1 + s\tau_v)(1 + s\tau_i)] \cong g_4 / [1 + s(\tau_v + \tau_i)]$ for small τ_v and τ_i .

The effect is equivalent to a series of a resistor with an inductor with inductance equal to $L = (\tau_v + \tau_i) / g_4$. To eliminate the excess phase effect, one can use a capacitor in parallel with the g_4 resistor. With the compensation capacitor C_c , we can write $I_z = (g_4 + sC_c) / [1 + s(\tau_v + \tau_i)] V_y$, which leads to $C_c = g_4(\tau_v + \tau_i)$.

3. Current-Mode Active Filters Using Single Dual-Output CCII

The current-mode filter configuration using a single DO-CCII is shown in Figure 2. Its general current transfer function can be derived as

$$\frac{I_o}{I_i} = \frac{y_2 y_4 y_6}{y_1 y_4 d + y_2 y_4 e + y_1 y_5 f + y_2 y_3 y_5} \quad (5)$$

$$d = y_2 + y_3 + y_5 \quad (6)$$

$$e = y_3 + y_5 + y_6 \quad (7)$$

$$f = y_2 + y_3 \quad (8)$$

Many types of filter can be realised by this circuit. Some are given in Table 1.

In the literature current-mode CCII-RC filters often take output currents from capacitor or resistor branches. Such current output methods are not suitable for

Type	Components					
General	y_1	y_2	y_3	y_4	y_5	y_6
LP1	SC_1	g_2	SC_3	∞	0	g_6
LP2	SC_1	g_2	SC_3	∞	g_5	g_6
LP3	g_1	∞	SC_3	g_4	sC_5	g_6
LP4	SC_1	g_2	SC_3	g_4	g_5	g_6
LP5	g_1	g_2	SC_3	g_4	sC_5	g_6
LP6	SC_1	g_2	g_3	g_4	sC_5	g_6
BP1	g_1	sC_2	SC_3	∞	g_5	g_6
BP2	g_1	∞	SC_3	sC_4	g_5	g_6
BP3	g_1	sC_2	SC_3	g_4	g_5	g_6
BP4	g_1	g_2	sC_3	sC_4	g_5	g_6
BP5	g_1	sC_2	g_3	g_4	sC_5	g_6
BP6	SC_1	g_2	g_3	sC_4	g_5	g_6
HP1	g_1	sC_2	g_3	sC_4	g_5	g_6
HP2	g_1	sC_2	g_3	g_4	g_5	SC_6
HP3	g_1	sC_2	g_3	∞	0	SC_6
HP4	g_1	sC_2	0	g_4	g_5	SC_6
HP5	g_1	g_2	g_3	SC_4	g_5	SC_6

Table 1 Filters generated from the topology in Figure 2

connection as coupling will occur if the driven stage does not have zero input impedance. Utilizing the current following and virtual grounding property of the CCII with Y terminal grounded, we may insert extra CCII's into the associated branches to take current outputs. But the nonidealities of these extra CCII's will severely degrade the filter performance and this method will also increase component count. The proposed filter structure in Figure 2 uses a multiple current output CCII and the filter current output can be taken directly from the output terminal.

For high-order filter design using the current transfer function, the proposed current to current biquad in Figure 2 can be cascaded directly. For the realization of a high-order lowpass voltage transfer function, we may start with a voltage to current section such as the one in [11], cascade it with the current to current sections in Figure 2 and end up with the current to voltage section in Figure 1. Note that in some applications, to take the

advantage of high performance of current-mode filters, people do design high-order voltage filters in this way, rather than by cascading voltage-to-voltage sections.

4. Conclusions

We have presented a new current to voltage lowpass filter using a single CCII. The filter has many attractive features such as low sensitivity, parasitic free, capable of both inverting and non-inverting output, easy to compensate for CCII gain inaccuracies and excess phase. It is particularly useful for sampled-data filtering and data converting systems as it can simultaneously perform lowpass filtering and interfacing between the current- and voltage-mode systems. A current-mode filter architecture using a single dual output CCII has also been proposed. The filter can be

cascaded directly due to the output taken from the CCII output terminal and has lower parasitic effects and lower component count than those taking current output from capacitor or resistor branches. We have shown the range of filter functions which are supported by the configuration. Using the two filters proposed as basic sections, both voltage and current high order transfer functions can be realised by cascading them. Finally, it should be noted that in practical implementations of these single amplifier filters, resistors are often replaced by MOSFETs in triode region and balanced/fully differential structure are used as is well known in MOSFET-C filter design [1].

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